

Lecture 10: Review of graph modeling and inference

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March 6, 2025

Main Problems

Main Problem

Input data: a weighted graph $G = (\mathcal{V}, W)$ with n nodes.

Issues:

- 1 Decide how well the two random graph models explain the data.
- 2 Partition the graph into two communities.
- 3 Construct an embedding $\{y_1, \dots, y_n\} \subset \mathbb{R}^d$ such that $W_{i,j} \sim \varphi(\|y_i - y_j\|)$ for some monotonically decreasing function φ .

Typical weight functions:

- 1 Exponential model: $\varphi(t) = Ce^{-t^2}$, for some $C > 0$.
- 2 Power law: $\varphi(t) = \frac{C}{t^p}$, for some $C > 0$ and $p > 0$.

Analysis

Three studies need to be done:

- 1 *Random graph hypothesis*: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques with their expectations under the two stochastic models, Erdős-Rényi and SSBM.

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- 1 *Random graph hypothesis*: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques with their expectations under the two stochastic models, Erdős-Rényi and SSBM.
- 2 Community Detection/Partition/Image Segmentation: Two classes of algorithms: spectral methods and SDP relaxations.

Analysis

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- ① *Random graph hypothesis*: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques with their expectations under the two stochastic models, Erdős-Rényi and SSBM.
- ② Community Detection/Partition/Image Segmentation: Two classes of algorithms: spectral methods and SDP relaxations.
- ③ Embeddings: *Laplacian eigenmaps*: The geometric graph is obtained by solving the bottom $d + 1$ eigenproblems for the normalized symmetric Laplacian $\tilde{\Delta} = I - D^{-1/2}WD^{-1/2}$. Additional algorithms: LLE and ISOMAP.

Distribution of Cliques

Expected Values

Let X_q denote the number of q -cliques in a random graph G . Then the expectation of X_q in $\mathcal{G}_{n,p}$ class is

$$\mathbb{E}[X_q] = \binom{n}{q} p^{q(q-1)/2}$$

The expectation of X_q in the class $\Gamma^{n,m}$ is approximated by the above formula for $p = \frac{2m}{n(n-1)}$:

$$\mathbb{E}[X_q] \approx \binom{n}{q} \left(\frac{2m}{n(n-1)} \right)^{q(q-1)/2} \sim \theta_q \frac{m^{q(q-1)/2}}{n^{q(q-2)}}$$

$$\mathbb{E}[X_3] \sim \theta \frac{m^3}{n^3}, \quad \mathbb{E}[X_4] \sim \theta \frac{m^6}{n^8}$$

3-Cliques and 4-cliques

Thresholds

Theorem

Let $m = m(n)$ be the number of edges in $\Gamma^{n,m}$.

- 1 If $m \gg n$ (i.e. $\lim_{n \rightarrow \infty} \frac{m}{n} = \infty$) then
 $\lim_{n \rightarrow \infty} \text{Prob}[G \in \Gamma^{n,m} \text{ has a 3-clique}] \rightarrow 1.$
- 2 If $m \ll n$ (i.e. $\lim_{n \rightarrow \infty} \frac{m}{n} = 0$) then
 $\lim_{n \rightarrow \infty} \text{Prob}[G \in \Gamma^{n,m} \text{ has a 3-clique}] \rightarrow 0.$

Theorem

Let $m = m(n)$ be the number of edges in $\Gamma^{n,m}$.

- 1 If $m \gg n^{4/3}$ (i.e. $\lim_{n \rightarrow \infty} \frac{m}{n^{4/3}} = \infty$) then
 $\lim_{n \rightarrow \infty} \text{Prob}[G \in \Gamma^{n,m} \text{ has a 4-clique}] \rightarrow 1.$
- 2 If $m \ll n^{4/3}$ (i.e. $\lim_{n \rightarrow \infty} \frac{m}{n^{4/3}} = 0$) then
 $\lim_{n \rightarrow \infty} \text{Prob}[G \in \Gamma^{n,m} \text{ has a 4-clique}] \rightarrow 0.$

3-Cliques and 4-Cliques

Behavior at the threshold

In general we obtain a "coarse threshold". Recall a Poisson process X with parameter λ has p.m.f. $Prob[X = k] = e^{-\lambda} \frac{\lambda^k}{k!}$.

Theorem

In $\mathcal{G}_{n,p}$,

- 1 For $p = \frac{c}{n}$, X_3 is asymptotically Poisson with parameter $\lambda = c^3/6$.
- 2 For $p = \frac{c}{n^{2/3}}$, X_4 is asymptotically Poisson with parameter $\lambda = c^6/24$.

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Theorem

In $\Gamma^{n,m}$,

- 1 For $m = cn$, X_3 is asymptotically Poisson with parameter $\lambda = 4c^3/3$.
- 2 For $m = cn^{4/3}$, X_4 is asymptotically Poisson with parameter $\lambda = 8c^6/3$.

Eigenvalues of Laplacians

$\Delta, L, \tilde{\Delta}$

What do we know about the set of eigenvalues of these matrices for a graph G with n vertices?

- 1 $\Delta = \Delta^T \geq 0$ and hence its eigenvalues are non-negative real numbers.
- 2 $eigs(\tilde{\Delta}) = eigs(L) \subset [0, 2]$.
- 3 0 is always an eigenvalue and its multiplicity equals the number of connected components of G ,

$$\dim \ker(\Delta) = \dim \ker(L) = \dim \ker(\tilde{\Delta}) = \# \text{connected components.}$$

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Let $0 = \lambda_0 \leq \lambda_1 \leq \dots \leq \lambda_{n-1}$ be the eigenvalues of $\tilde{\Delta}$. Denote

$$\lambda(G) = \max_{1 \leq i \leq n-1} |1 - \lambda_i|.$$

Note $\sum_{i=1}^{n-1} \lambda_i = \text{trace}(\tilde{\Delta}) = n$. Hence the average eigenvalue is about 1. $\lambda(G)$ is called *the absolute gap* and measures the spread of eigenvalues away from 1.

The spectral absolute gap

 $\lambda(G)$

The main result in [9]) says that for connected graphs w/h.p.:

$$\lambda_1 \geq 1 - \frac{C}{\sqrt{\text{Average Degree}}} = 1 - \frac{C}{\sqrt{p(n-1)}} = 1 - C\sqrt{\frac{n}{2m}}.$$

Theorem (For class $\mathcal{G}_{n,p}$)

Fix $\delta > 0$ and let $p > (\frac{1}{2} + \delta)\log(n)/n$. Let $d = p(n-1)$ denote the expected degree of a vertex. Let \tilde{G} be the giant component of the Erdős-Rényi graph. For every fixed $\varepsilon > 0$, there is a constant $C = C(\delta, \varepsilon)$, so that

$$\lambda(\tilde{G}) \leq \frac{C}{\sqrt{d}}$$

with probability at least $1 - Cn \exp(-(2 - \varepsilon)d) - C \exp(-d^{1/4} \log(n))$.

Connectivity threshold: $p \sim \frac{\log(n)}{n}$.

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Theorem (For class $\Gamma^{n,m}$)

Fix $\delta > 0$ and let $m > \frac{1}{2}(\frac{1}{2} + \delta)n \log(n)$. Let $d = \frac{2m}{n}$ denote the expected degree of a vertex. Let \tilde{G} be the giant component of the Erdős-Rényi graph. For every fixed $\varepsilon > 0$, there is a constant $C = C(\delta, \varepsilon)$, so that

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Connectivity threshold: $m \sim \frac{1}{2}n \log(n)$.

Isometric Embeddings with Partial Data

Linear constraints

Given any set of vectors $\{y_1, \dots, y_n\}$ and their associated matrix $Y = [y_1 | \dots | y_n]$ their invariant to the action of the rigid transformations (translations, rotations, and reflections) is the Gram matrix of the centered system:

$$G = \left(I - \frac{1}{n} \mathbf{1} \cdot \mathbf{1}^T\right) Y^T Y \left(I - \frac{1}{n} \mathbf{1} \cdot \mathbf{1}^T\right) =: LY^T YL, \quad L = I - \frac{1}{n} \mathbf{1} \cdot \mathbf{1}^T.$$

On the other hand, the distance between points i and j can be computed by:

$$d_{i,j}^2 = \|y_i - y_j\|^2 = G_{i,i} - G_{i,j} + G_{j,j} - G_{j,i} = e_{ij}^T G e_{ij}$$

where

$$e_{ij} = \delta_i - \delta_j = [0 \dots 0 \ 1 \dots -1 \ 0 \dots 0]^T$$

where 1 is on position i , -1 is on position j , and 0 everywhere else.

Almost Isometric Embeddings with Partial Data

The SDP Problem

Reference [10] proposes to find the matrix G by solving the following Semi-Definite Program:

$$\begin{aligned} \min \quad & \text{trace}(G) \\ G = G^T \geq 0 \\ G \cdot \mathbf{1} = 0 \\ |\langle Ge_{ij}, e_{ij} \rangle - \tilde{d}_{i,j}^2| \leq \varepsilon, \quad (i, j) \in \Theta \end{aligned}$$

where $\tilde{d}_{i,j}^2$ are noisy estimates $d_{i,j}$ and ε is the maximum noise level. The trace promotes low rank in this optimization. However, this is basically a feasibility problem: Decrease ε to the minimum value where a feasible solution exists. With probability 1 that is unique.

How to do this: Use CVX with Matlab.

Geometric Graph Embedding

Gram matrix factorization: The Algorithm

Algorithm

Input: Symmetric $n \times n$ Gram matrix G .

- ① *Compute the eigendecomposition of G , $G = Q\Lambda Q^T$ with diagonal of Λ sorted in a descending order;*
- ② *Determine the number d of significant positive eigenvalues;*
- ③ *Partition*

$$Q = [Q_1 \quad Q_2] \quad , \text{ and } \Lambda = \begin{bmatrix} \Lambda_1 & 0 \\ 0 & \Lambda_2 \end{bmatrix}$$

where Q_1 contains the first d columns of Q , and Λ_1 is the $d \times d$ diagonal matrix of significant positive eigenvalues of G .

- ④ *Compute:*

$$Y = \Lambda_1^{1/2} Q_1^T$$

Output: Dimension d and $d \times n$ matrix Y of vectors $Y = [y_1 | \cdots | y_n]$

Nearly Isometric Embeddings with Partial Data

Stability to Noise

[10] proves the following stability result in the case of partial measurements. Here we denote $\Theta_r = \{(i, j) , \|y_i - y_j\| \leq r\}$ the set of all pairs of points at distance at most r .

Theorem

Let $\{y_1, \dots, y_n\}$ be n nodes distributed uniformly at random in the hypercube $[-0.5, 0.5]^d$. Further, assume that we are given noisy measurement of all distances in Θ_r for some $r \geq 10\sqrt{d}(\log(n)/n)^{1/d}$ and the induced geometric graph of edges is connected. Let $\tilde{d}_{i,j}^2 = d_{i,j}^2 + \nu_{i,j}$ with $|\nu_{i,j}| \leq \varepsilon$. Then with high probability, the error distance between the estimated $\hat{Y} = [\hat{y}_1 | \dots | \hat{y}_n]$ returned by the SDP-based algorithm and the correct coordinate matrix $Y = [y_1 | \dots | y_n]$ is upper bounded as

$$\|L\hat{Y}^T\hat{Y}L - LY^TYL\|_1 \leq C_1(nr^d)^5 \frac{\varepsilon}{r^4}.$$

Optimization Criterion

Assume $\mathcal{G} = (\mathcal{V}, W)$ is a undirected weighted graph with n nodes and weight matrix W .

We interpret $W_{i,j}$ as the *similarity* between nodes i and j . The larger the weight the more similar the nodes, and the closer they are in a geometric graph embedding.

Thus we look for a dimension $d > 0$ and a set of points

$\{y_1, y_2, \dots, y_n\} \subset \mathbb{R}^d$ so that $d_{i,j} = \|y_i - y_j\|$'s is small for large weight $W_{i,j}$. This means we want to minimize

$$J(y_1, y_2, \dots, y_n) = \sum_{1 \leq i, j \leq n} W_{i,j} \|y_i - y_j\|^2,$$

To avoid trivial solution $Y = 0$ we impose a normalization condition:

$$YDY^T = I_d.$$

The Optimization Problem

Combining the criterion with the constraint:

$$(LE) : \begin{array}{ll} \text{minimize} & \text{trace} \left\{ Y \Delta Y^T \right\} \\ \text{subject to} & Y D Y^T = I_d \end{array}$$

we obtained the *Laplacian Eigenmap* problem.

Good news: The optimizer Y is obtained by solving an eigenproblem.

Laplacian Eigenmaps Embedding

Algorithm

Algorithm (Laplacian Eigenmaps)

Input: Weight matrix W , target dimension d

- 1 Construct the diagonal matrix $D = \text{diag}(D_{ii})_{1 \leq i \leq n}$, where $D_{ii} = \sum_{k=1}^n W_{i,k}$.
- 2 Construct the normalized Laplacian $\tilde{\Delta} = I - D^{-1/2}WD^{-1/2}$.
- 3 Compute the bottom $d + 1$ eigenvectors e_1, \dots, e_{d+1} , $\tilde{\Delta}e_k = \lambda_k e_k$, $0 = \lambda_1 \cdots \lambda_{d+1}$.

Laplacian Eigenmaps Embedding

Algorithm-cont's

Algorithm (Laplacian Eigenmaps - cont'd)

- ④ Construct the $d \times n$ matrix Y ,

$$Y = \begin{bmatrix} e_2 \\ \vdots \\ e_{d+1} \end{bmatrix} D^{-1/2}$$

- ⑤ The new geometric graph is obtained by converting the columns of Y into n d -dimensional vectors:

$$\begin{bmatrix} y_1 & | & \cdots & | & y_n \end{bmatrix} = Y$$

Output: Set of points $\{y_1, y_2, \dots, y_n\} \subset \mathbb{R}^d$.

Problem Formulation

Given: It is assumed that we are given a set of points $\{x_1, \dots, x_n\} \subset \mathbb{R}^N$, or a weight matrix W , where $W_{i,j}$ is inverse monotonically dependent to distances $\|x_i - x_j\|$; the smaller the distance $\|x_i - x_j\|$ the larger the weight $W_{i,j}$.

Target: We look for a dimension $d > 0$ and a set of points $\{y_1, y_2, \dots, y_n\} \subset \mathbb{R}^d$ so that all $d_{i,j} = \|y_i - y_j\|$'s are compatible with the raw data.

Approaches:

- 1 Principal Component Analysis
- 2 Independent Component Analysis
- 3 Laplacian Eigenmaps
- 4 Local Linear Embeddings (LLE)
- 5 Isomaps

Principal Component Analysis

Algorithm

Algorithm (Principal Component Analysis)

Input: Data vectors $\{x_1, \dots, x_n\} \in \mathbb{R}^N$; dimension d .

- ① *If affine subspace is the goal, append '1' at the end of each data vector.*
- ① *Compute the sample covariance matrix*

$$R = \sum_{k=1}^n x_k x_k^T$$

- ② *Solve the eigenproblems $Re_k = \sigma_k^2 e_k$, $1 \leq k \leq N$, order eigenvalues $\sigma_1^2 \geq \sigma_2^2 \geq \dots \geq \sigma_N^2$ and normalize the eigenvectors $\|e_k\|_2 = 1$.*

Principal Component Analysis

Algorithm - cont'ed

Algorithm (Principal Component Analysis)

- ③ *Construct the co-isometry*

$$U = \begin{bmatrix} e_1^T \\ \vdots \\ e_d^T \end{bmatrix}.$$

- ④ *Project the input data*

$$y_1 = Ux_1, \quad y_2 = Ux_2, \quad \dots, \quad y_n = Ux_n.$$

Output: Lower dimensional data vectors $\{y_1, \dots, y_n\} \in \mathbb{R}^d$.

The orthogonal projection is given by $P = \sum_{k=1}^d e_k e_k^T$ and the optimal subspace is $V = \text{Ran}(P)$

Dimension Reduction using Laplacian Eigenmaps

Algorithm

Algorithm (Dimension Reduction using Laplacian Eigenmaps)

Input: A geometric graph $\{x_1, x_2, \dots, x_n\} \subset \mathbb{R}^N$. Parameters: threshold τ , weight coefficient α , and dimension d .

- 1 Compute the set of pairwise distances $\|x_i - x_j\|$ and convert them into a set of weights:

$$W_{i,j} = \begin{cases} \exp(-\alpha\|x_i - x_j\|^2) & \text{if } \|x_i - x_j\| \leq \tau \\ 0 & \text{if otherwise} \end{cases}$$

- 2 Compute the $d + 1$ bottom eigenvectors of the normalized Laplacian matrix $\tilde{\Delta} = I - D^{-1/2}WD^{-1/2}$, $\tilde{\Delta}e_k = \lambda_k e_k$, $1 \leq k \leq d + 1$, $0 = \lambda_0 \leq \dots \leq \lambda_{d+1}$, where $D = \text{diag}(\sum_{k=1}^n W_{i,k})_{1 \leq i \leq n}$.

Dimension Reduction using Laplacian Eigenmaps

Algorithm - cont'd

Algorithm (Dimension Reduction using Laplacian Eigenmaps-cont'd)

- ③ Construct the $d \times n$ matrix Y ,

$$Y = \begin{bmatrix} e_2^T \\ \vdots \\ e_{d+1}^T \end{bmatrix} D^{-1/2}$$

- ④ The new geometric graph is obtained by converting the columns of Y into n d -dimensional vectors:

$$\begin{bmatrix} y_1 & | & \cdots & | & y_n \end{bmatrix} = Y$$

Output: $\{y_1, \dots, y_n\} \subset \mathbb{R}^d$.

Dimension Reduction using Isomaps

Algorithm

Algorithm (Dimension Reduction using Isomap)

Input: A geometric graph $\{x_1, x_2, \dots, x_n\} \subset \mathbb{R}^N$. Parameters: neighborhood size K and dimension d .

- 1 Construct the symmetric matrix S of squared pairwise distances:
 - 1 Construct the sparse matrix T , where for each node i find the nearest K neighbors \mathcal{V}_i and set $T_{i,j} = \|x_i - x_j\|_2$, $j \in \mathcal{V}_i$.
 - 2 For any pair of two nodes (i, j) compute $d_{i,j}$ as the length of the shortest path, $\sum_{p=1}^L T_{k_{p-1}, k_p}$ with $k_0 = i$ and $k_L = j$, using e.g. Dijkstra's algorithm.
 - 3 Set $S_{i,j} = d_{i,j}^2$.

Dimension Reduction using Isomaps

Algorithm - cont'd

Algorithm (Dimension Reduction using Isomap - cont'd)

- 2 Compute the Gram matrix G :

$$\rho = \frac{1}{2n} \mathbf{1}^T \cdot S \cdot \mathbf{1}, \quad \nu = \frac{1}{n} (S \cdot \mathbf{1} - \rho \mathbf{1})$$








$$G = \frac{1}{2} \nu \cdot \mathbf{1}^T + \frac{1}{2} \mathbf{1} \cdot \nu^T - \frac{1}{2} S$$

- 3 Find the top d eigenvectors of G , say e_1, \dots, e_d so that $GE = E\Lambda$, form the matrix Y and then collect the columns:

$$Y = \Lambda^{1/2} \begin{bmatrix} e_1^T \\ \vdots \\ e_d^T \end{bmatrix} = \begin{bmatrix} y_1 & | & \cdots & | & y_n \end{bmatrix}$$

Output: $\{v_1, \dots, v_n\} \subset \mathbb{R}^d$.

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