Discovery Thread: Project 2

In this project you will apply the techniques for random graphs model selection and community detection on a specific data set.

Three files are assigned to your teams: a DataFile *.dat , and two images *.bmp as described next.

- 1. The image file Phantom^{*}.bmp contains a $n \times n$ black-and-white image that is utilized as reference signal for your project. You can load this image in Matlab using imread() function. Note the entries are unsigned 8-bit integers (hence in the range 0 .. 255).
- 2. The graph weight matrix file WeightMatrixForImage*Noisy.dat . This text file has the following format:

First line: n
Second line: W(1,1) W(1,2) W(1,3) ... W(1,n)
Third line: W(2,1) W(2,2) W(2,3) ... W(2,n)
...
Line n+1: W(n,1) W(n,2) W(n,3) ... W(n,n)

where the entries W(i, j) were computed based on the reference Phantom image. Specifically $W(i, j) = exp(-|I(i) - I(j)|/20 - ||i - j||^2/10)$ where I(i), I(j) are noisy intensities of pixels *i* and *j* of image Phantom*.bmp.

3. The image HighResNoisyPhantom*.bmp is the upsampled noisy reference image Phantom*.bmp.

In your project n = 1024 and corresponds to a 32×32 image. Vertices are pixels indexed row-wise from left to right:

 $vertex_1 = pixel(1,1)$, $vertex_2 = pixel(1,2)$, $vertex_3 = pixel(1,3)$ \cdots $vertex_{33} = pixel(2,1)$ \cdots

On the weighted undirected graph dataset assigned to your project perform the following three tasks:

I. Random graph model testing: Point Estimation:

- 1. Under the Erdos-Renyi random graph model, estimate the parameter *p*. Compute the estimated number of 3-cliques and 4-cliques and compare them to the actual numbers of 3-cliques and 4-cliques in your data set.
- 2. Under the SSBM random graph model, estimate the parameters a and b based on the number of vertices, edges, and 3-cliques. Compute the estimated number of 4-cliques (under the SSBM model) and compare this predicted number to the actual number of 4-cliques.

Sequence of 4-cliques prediction:

1. Create an ordered sequence of edges accoring to their weight. Specifically, order the edges according to the weight, starting with the largest weight first and then continue in a monotonic decreasing order. To do so, create a data file, say graph.dat, from the data file assigned to your project, that lists the edges in the appropriate order, and has the following format:

First line: n m
Second line: Edge1Vertex1 Edge1Vertex2
Third line: Edge2Vertex1 Edge2Vertex2
...
m+1st line: EdgemVertex1 EdgemVertex2

- 2. For the sequence of edges (and graphs) perform the following computations:
 - (a) Under the Erdos-Renyi random graph model, for each graph in the sequence, estimate the parameter p, and compute the expectation of the number of 4-cliques; On the log-log plot, determine the best linear fit, $log(X_4) = a_{ER}log(m) + b_{ER}$, where m is the running number of edges; discard the first values of m when there are no 4-cliques.
 - (b) Under the SSBM random graph model, for each graph in the sequence, estimate parameters a and b and compute the expectation of the number of 4-cliques; On the log-log plot, determine the best linear fit, $log(X_4) = a_{SSBM}log(m) + b_{SSBM}$, where m is the running number of edges; discard the first values of m when there are no 4-cliques.
 - (c) For each graph in the sequence, compute the actual number of 4cliques, $X_4(m)$, and determine the best linear fit, $log(X_4) = a_0 log(m) + b_0$, where m is the running number of edges; discard the first values of m when there are no 4-cliques.
- 3. Overlay in the same plot the graphs of $log(X_4)$ and the prediction under Erdos-Renyi and SSBM models of the number of 4-cliques. Print also the parameters a_{ER}, a_{SSBM}, a_0 and b_{ER}, b_{SSBM}, b_0 .

II. Community detection:

Implement the six community discovery algorithms (partition algorithms) and run them on your project data set.

Specifically, implement:

- 1. Spectral methods using: W, Δ , and $\tilde{\Delta}$
- 2. SDP relaxation algorithms using: W, Δ , and $\tilde{\Delta}$

Recall rasterisation is done row by row.

For each of the six algorithms above, determine sets S and $\overline{S} = \{1, 2, ..., n\} \setminus S$. Then map back onto the noisy image the two sets, and overlay the resulting partition.

For easy visualization, use the High resolution image (which is 1024×1024 pixels). Each pixel in the standard (low-res) 32×32 image is upsampled to (i.e., replaced by) a 32×32 block of pixels in the High resolution image. For each algorithm present the following images images:

- 1. The High resolution noisy and/or clean image
- 2. The indicator image of the partition sets, as a two-tone image;
- 3. Overlay of the partition indicator to the noisy High resolution image