

Math 420, Spring 2020 Third Team Homework

due Tuesday, 3 March 2020

Consider the text files: Target = 'Cloud_psb420.coord' , Source0 = 'EstimatedCloud_psb420.coord' and nine additional files Source1 = 'NoisyCloud1_psb420.coord' , ..., Source9 = 'NoisyCloud9_psb420.coord' assigned to this homework. These files have the following format:

```
line 1: x1 y1 z1
line 2: x2 y2 z2
line 3: x3 y3 z3
line 4: x4 y4 z4
...
line n: xn yn zn
```

where n denotes the number of vertices (points) of a 3D geometric graph, and each line contains the coordinates of these points; the i^{th} line contains the (x, y, z) coordinates of the i^{th} point.

The files whose name contains 'Noisy' include noisy measurements of these coordinates.

Your homework is to implement a Matlab code that performs a full alignment of each of the 10 source files (Source0 to Source 9) with the target file. In each case obtain the alignment error and create a movie file that illustrates the transformation.

I. For each pair of files (Source j , Target), with $j = 0, 1, 2, \dots, 9$:

1. Implement the full alignment algorithm and estimate $(\hat{Q}, \hat{z}, \hat{a})$
2. Compute the alignment error $\|\hat{a}\hat{Q}(X - \hat{z}1^T) - Y\|_F$
3. Create a .avi file using the videoWriter in Matlab, saving about 101 images (plots) where the k^{th} image (k running from 0 to 100) defines the $t = k/100$ interpolation:

$$X(t) = a(t)Q(t)(X - z(t)1^T) , \quad a(t) = 1 - t + t\hat{a} , \quad Q(t) = \expm(t \cdot \logm(\hat{Q})) , \quad z(t) = t\hat{z}$$

where \expm and \logm are Matlab matrix exponential and matrix logarithm functions. Each image should contain a plot of the geometric graph contained in $X(t)$. Plot the graph using the closest $K = 4$ neighbors procedure used in solo Homework 2.

II. Once the 10 pairs (Source j , Target) files have been processed, plot the alignment error as function of index j , where j runs from 0 to 9.

III. What type of dependency $error = error(j)$ do you obtain? That is, is it linear, polynomial or exponential? Try also $error = error(9 - j)$. j measures the level of noise: the larger the value the larger the noise.