Lecture 12: Review of nonlinear geometric graph modeling

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Problem Formulation	Predictions in Random Graphs	SDP-based Embedding	Laplacian Eigenmaps	Dimension Reduction Tech
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Main Problem

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Given a weighted graph $G = (\mathcal{V}, W)$ with *n* nodes, find a dimension *d* and a set of *n* points $\{y_1, \dots, y_n\} \subset \mathbb{R}^d$ such that $W_{i,j} = \varphi(||y_i - y_j||)$ for some monotonically decreasing function φ . Additionally test how a random graph model explains the data.

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Thus we look for a dimension d > 0 and a set of points $\{y_1, y_2, \dots, y_n\} \subset \mathbb{R}^d$ so that all $d_{i,j} = ||y_i - y_j||$'s are compatible with weighted graph.

Typical weight functions:

- Exponential model: $\varphi(t) = Ce^{-t^2}$, for some C > 0.
- 2 Power law: $\varphi(t) = \frac{C}{t^p}$, for some C > 0 and p > 0.

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Analysis				

Three studies need to be done:

Random graph hypothesis: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques and spectral gap to the expected ones for G_{n,p} and Γ^{n,m}.

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- **2** SDP optimization approach: Solve for the Gram matrix G that optimizes a Semi-Definite Program; Find its effective rank and then perform the SVD of $G = Y^T Y$ to find the geometric graph.

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Three studies need to be done:

- Random graph hypothesis: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques and spectral gap to the expected ones for $\mathcal{G}_{n,p}$ and $\Gamma^{n,m}$.
- **2** SDP optimization approach: Solve for the Gram matrix G that optimizes a Semi-Definite Program; Find its effective rank and then perform the SVD of $G = Y^T Y$ to find the geometric graph.

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Distributic	on of Cliques			

Let X_q denote the number of *q*-cliques in a random graph *G*. Then the expectation of X_q in $\mathcal{G}_{n,p}$ class is

$$\mathbb{E}[X_q] = \begin{pmatrix} n \\ q \end{pmatrix} p^{q(q-1)/2}$$

The expectation of X_q in the class $\Gamma^{n,m}$ is approximated by the above formula for $p = \frac{2m}{n(n-1)}$:

$$\mathbb{E}[X_q] \approx \binom{n}{q} \left(\frac{2m}{n(n-1)}\right)^{q(q-1)/2} \sim \theta_q \frac{m^{q(q-1)/2}}{n^{q(q-2)}}$$
$$\mathbb{E}[X_3] \sim \theta \frac{m^3}{n^3} \quad , \quad \mathbb{E}[X_4] \sim \theta \frac{m^6}{n^8}$$

Expected Values

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3-Cliques and 4-cliques Thresholds

Theorem

Let m = m(n) be the number of edges in $\Gamma^{n,m}$.

• If $m \gg n$ (i.e. $\lim_{n\to\infty} \frac{m}{n} = \infty$) then $\lim_{n\to\infty} Prob[G \in \Gamma^{n,m} has a 3 - clique] \to 1.$

2 If
$$m \ll n$$
 (i.e. $\lim_{n\to\infty} \frac{m}{n} = 0$) then
 $\lim_{n\to\infty} Prob[G \in \Gamma^{n,m} has a 3 - clique] \to 0.$

Theorem

Let m = m(n) be the number of edges in Γ^{n,m}.
If m ≫ n^{4/3} (i.e. lim_{n→∞} m/(n^{4/3}) = ∞) then lim_{n→∞} Prob[G ∈ Γ^{n,m} has a 4 - clique] → 1.
If m ≪ n^{4/3} (i.e. lim_{n→∞} m/(n^{4/3}) = 0) then lim_{n→∞} Prob[G ∈ Γ^{n,m} has a 4 - clique] → 0.

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3-Cliques and 4-Cliques Behavior at the threshold

In general we obtain a "coarse threshold". Recall a Poisson process X with parameter λ has p.m.f. $Prob[X = k] = e^{-\lambda} \frac{\lambda^k}{k!}$.

Theorem

In $\mathcal{G}_{n,p}$,

• For $p = \frac{c}{n}$, X_3 is asymptotically Poisson with parameter $\lambda = c^3/6$.

2 For $p = \frac{c}{n^{2/3}}$, X_4 is asymptotically Poisson with parameter $\lambda = c^6/24$.

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Theorem

In $\Gamma^{n,m}$,

For m = cn, X₃ is asymptotically Poisson with parameter λ = 4c³/3.
 For m = cn^{4/3}, X₄ is asymptotically Poisson with parameter λ = 8c⁶/3.

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Eigenvalues of Laplacians $\Delta, L, \tilde{\Delta}$

What do we know about the set of eigenvalues of these matrices for a graph G with n vertices?

- $\label{eq:alpha} \begin{tabular}{ll} \bullet & \Delta = \Delta^{\mathcal{T}} \geq 0 \mbox{ and hence its eigenvalues are non-negative real numbers. } \end{tabular}$
- eigs($\tilde{\Delta}$) = eigs(L) \subset [0, 2].
- 0 is always an eigenvalue and its multiplicity equals the number of connected components of G,

 $\dim \ker(\Delta) = \dim \ker(L) = \dim \ker(\tilde{\Delta}) = \#$ connected components.

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Let $0 = \lambda_0 \leq \lambda_1 \leq \cdots \leq \lambda_{n-1}$ be the eigenvalues of $\tilde{\Delta}$. Denote

$$\lambda(G) = \max_{1 \le i \le n-1} |1 - \lambda_i|.$$

Note $\sum_{i=1}^{n-1} \lambda_i = trace(\tilde{\Delta}) = n$. Hence the average eigenvalue is about 1. $\lambda(G)$ is called *the absolute gap* and measures the spread of eigenvalues away from 1. Radu Balan (UMD) MATH 420: Nonlinear modeling May 3, 2018

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The spectral absolute gap $\lambda(G)$

The main result in [9]) says that for connected graphs w/h.p.:

$$\lambda_1 \geq 1 - rac{\mathcal{C}}{\sqrt{ ext{Average Degree}}} = 1 - rac{\mathcal{C}}{\sqrt{\mathcal{p}(n-1)}} = 1 - \mathcal{C}\sqrt{rac{n}{2m}}.$$

Theorem (For class $\mathcal{G}_{n,p}$)

Fix $\delta > 0$ and let $p > (\frac{1}{2} + \delta)\log(n)/n$. Let d = p(n-1) denote the expected degree of a vertex. Let \tilde{G} be the giant component of the Erdös-Rényi graph. For every fixed $\varepsilon > 0$, there is a constant $C = C(\delta, \varepsilon)$, so that

$$\lambda(\tilde{G}) \leq \frac{C}{\sqrt{d}}$$

with probability at least $1 - Cn \exp(-(2 - \varepsilon)d) - C \exp(-d^{1/4}\log(n))$.

Connectivity threshold: $p \sim \frac{\log(n)}{n}$.

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Theorem (For class $\Gamma^{n,m}$)

Fix $\delta > 0$ and let $m > \frac{1}{2}(\frac{1}{2} + \delta)n \log(n)$. Let $d = \frac{2m}{n}$ denote the expected degree of a vertex. Let \tilde{G} be the giant component of the Erdös-Rényi graph. For every fixed $\varepsilon > 0$, there is a constant $C = C(\delta, \varepsilon)$, so that

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Connectivity threshold: $m \sim \frac{1}{2} n \log(n)$.

Isometric Embeddings with Partial Data Linear constraints

Given any set of vectors $\{y_1, \dots, y_n\}$ and their associated matrix $Y = [y_1| \dots |y_n]$ their invariant to the action of the rigid transformations (translations, rotations, and reflections) is the Gram matrix of the centered system:

$$G = (I - \frac{1}{n} 1 \cdot 1^{T}) Y^{T} Y (I - \frac{1}{n} 1 \cdot 1^{T}) =: LY^{T} Y L \quad , \quad L = I - \frac{1}{n} 1 \cdot 1^{T}$$

On the other hand, the distance between points i and j can be computed by:

$$d_{i,j}^2 = \|y_i - y_j\|^2 = G_{i,i} - G_{i,j} + G_{j,j} - G_{j,i} = e_{ij}^T G e_{ij}$$

where

$$e_{ij} = \delta_i - \delta_j = [0 \cdots 0 \ 1 \cdots - 1 \ 0 \cdots 0]^T$$

where 1 is on position i, -1 is on position j, and 0 everywhere else.



Almost Isometric Embeddings with Partial Data The SDP Problem

Reference [10] proposes to find the matrix G by solving the following Semi-Definite Program:

$$egin{aligned} & \min & trace(G) \ & G &= G^T \geq 0 \ & G \cdot 1 &= 0 \ & |\langle Ge_{ij}, e_{ij}
angle - ilde{d}_{i,j}^2| \leq arepsilon \;, \; (i,j) \in \Theta \end{aligned}$$

where $\tilde{d}_{i,j}^2$ are noisy estimates $d_{i,j}$ and ε is the maximum noise level. The trace promotes low rank in this optimization. However, this is basically a feasibility problem: Decrease ε to the minimum value where a feasible solution exists. With probability 1 that is unique. How to do this: Use CVX with Matlab.

Geometric Graph Embedding Gram matrix factorization: The Algorithm Algorithm

Input: Symmetric $n \times n$ Gram matrix G.

- Compute the eigendecomposition of G, G = QΛQ^T with diagonal of Λ sorted in a descending order;
- 2 Determine the number d of significant positive eigevalues;

In Partition

$$Q = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix}$$
 , and $\Lambda = \begin{bmatrix} \Lambda_1 & 0 \\ 0 & \Lambda_2 \end{bmatrix}$

where Q_1 contains the first d columns of Q, and Λ_1 is the $d \times d$ diagonal matrix of significant positive eigenvalues of G.

Compute:

$$Y = \Lambda_1^{1/2} Q_1^T$$

Output: Dimension d and d × n matrix Y of vectors $Y = [y_1| \cdots |y_n]$

Nearly Isometric Embeddings with Partial Data Stability to Noise

[10] proves the following stability result in the case of partial measurements. Here we denote $\Theta_r = \{(i,j), ||y_i - y_j|| \le r\}$ the set of all pairs of points at distance at most r.

Theorem

Let $\{y_1, \dots, y_n\}$ be n nodes distributed uniformly at random in the hypercube $[-0.5, 0.5]^d$. Further, assume that we are given noisy measurement of all distances in Θ_r for some $r \ge 10\sqrt{d}(\log(n)/n)^{1/d}$ and the induced geometric graph of edges is connected. Let $\tilde{d}_{i,j}^2 = d_{i,j}^2 + \nu_{i,j}$ with $|\nu_{i,j}| \le \varepsilon$. Then with high probability, the error distance between the estimated $\hat{Y} = [\hat{y}_1, |\cdots|\hat{y}_n]$ returned by the SDP-based algorithm and the correct coordinate matrix $Y = [y_1|\cdots|y_n]$ is upper bounded as

$$\|L\hat{Y}^T\hat{Y}L - LY^TYL\|_1 \leq C_1(nr^d)^5\frac{\varepsilon}{r^4}.$$

Optimization Criterion

Assume $\mathcal{G} = (\mathcal{V}, W)$ is a undirected weighted graph with *n* nodes and weight matrix *W*.

We interpret $W_{i,j}$ as the *similarity* between nodes *i* and *j*. The larger the weight the more similar the nodes, and the closer they are in a geometric graph embedding.

Thus we look for a dimension d > 0 and a set of points $\{y_1, y_2, \dots, y_n\} \subset \mathbb{R}^d$ so that $d_{i,j} = ||y_i - y_j||$'s is small for large weight $W_{i,j}$. This means we want to minimize

$$J(y_1, y_2, \cdots, y_n) = \sum_{1 \leq i,j \leq n} W_{i,j} ||y_i - y_j||^2,$$

To avoid trivial solution Y = 0 we impose a normalization condition:

$$YDY^T = I_d.$$

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The Optimization Problem

Combining the criterion with the constraint:

$$(LE) : \begin{array}{ll} \text{minimize} & trace \left\{ Y \Delta Y^T \right\} \\ \text{subject to} & Y D Y^T = I_d \end{array}$$

we obtained the Laplacian Eigenmap problem.

Good news: The optimizer Y is obtaind by solving an eigenproblem.

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Laplacian Eigenmaps Embedding Algorithm

Algorithm (Laplacian Eigenmaps)

Input: Weight matrix W, target dimension d

- Construct the diagonal matrix $D = diag(D_{ii})_{1 \le i \le n}$, where $D_{ii} = \sum_{k=1}^{n} W_{i,k}$.
- **2** Construct the normalized Laplacian $\tilde{\Delta} = I D^{-1/2} W D^{-1/2}$.
- Compute the bottom d + 1 eigenvectors e_1, \dots, e_{d+1} , $\tilde{\Delta}e_k = \lambda_k e_k$, $0 = \lambda_1 \cdots \lambda_{d+1}$.

Laplacian Eigenmaps Embedding Algorithm-cont's

Algorithm (Laplacian Eigenmaps - cont'd)

• Construct the $d \times n$ matrix Y,

$$Y = \begin{bmatrix} e_2 \\ \vdots \\ e_{d+1} \end{bmatrix} D^{-1/2}$$

The new geometric graph is obtained by converting the columns of Y into n d-dimensional vectors:

$$\left[\begin{array}{cccc} y_1 & | & \cdots & | & y_n \end{array}\right] = Y$$

Output: Set of points $\{y_1, y_2, \cdots, y_n\} \subset \mathbb{R}^d$.

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Problem Formulation

Given: It is assumed that we are given a set of points $\{x_1, \dots, x_n\} \subset \mathbb{R}^N$, or a weight matrix W, where $W_{i,j}$ is inverse monotonically dependent to distances $||x_i - x_j||$; the smaller the distance $||x_i - x_j||$ the larger the weight $W_{i,j}$.

Target: We look for a dimension d > 0 and a set of points

 $\{y_1, y_2, \cdots, y_n\} \subset \mathbb{R}^d$ so that all $d_{i,j} = ||y_i - y_j||$'s are compatible with the raw data.

Approaches:

- Principal Component Analysis
- Independent Component Analysis
- 4 Laplacian Eigenmaps
- 4 Local Linear Embeddings (LLE)
- Isomaps

Principal Component Analysis Algorithm

Algorithm (Principal Component Analysis)

Input: Data vectors $\{x_1, \cdots, x_n\} \in \mathbb{R}^N$; dimension d.

- If affine subspace is the goal, append '1' at the end of each data vector.
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$$R = \sum_{k=1}^{n} x_k x_k^T$$

2 Solve the eigenproblems $Re_k = \sigma_k^2 e_k$, $1 \le k \le N$, order eigenvalues $\sigma_1^2 \ge \sigma_2^2 \ge \cdots \ge \sigma_N^2$ and normalize the eigenvectors $||e_k||_2 = 1$.

Principal Component Analysis Algorithm - cont'ed

Algorithm (Principal Component Analysis)

3 Construct the co-isometry

$$\mathcal{U} = \begin{bmatrix} e_1^T \\ \vdots \\ e_d^T \end{bmatrix}$$

Project the input data

$$y_1 = Ux_1 , y_2 = Ux_2 , \cdots , y_n = Ux_n.$$

Output: Lower dimensional data vectors $\{y_1, \dots, y_n\} \in \mathbb{R}^d$.

The orthogonal projection is given by $P = \sum_{k=1}^{d} e_k e_k^T$ and the optimal subspace is V = Ran(P).

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Dimension Reduction using Laplacian Eigenmaps Algorithm

Algorithm (Dimension Reduction using Laplacian Eigenmaps)

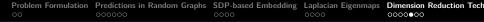
Input: A geometric graph $\{x_1, x_2, \dots, x_n\} \subset \mathbb{R}^N$. Parameters: threshold τ , weight coefficient α , and dimension d.

Compute the set of pairwise distances ||x_i - x_j|| and convert them into a set of weights:

$$W_{i,j} = \begin{cases} exp(-\alpha ||x_i - x_j||^2) & \text{if } ||x_i - x_j|| \le \tau \\ 0 & \text{if } & \text{otherwise} \end{cases}$$

② Compute the d + 1 bottom eigenvectors of the normalized Laplacian matrix $\tilde{\Delta} = I - D^{-1/2} W D^{-1/2}$, $\tilde{\Delta} e_k = \lambda_k e_k$, $1 \le k \le d + 1$, $0 = \lambda_0 \le \cdots \le \lambda_{d+1}$, where $D = diag(\sum_{k=1}^n W_{i,k})_{1 \le i \le n}$.

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Dimension Reduction using Laplacian Eigenmaps Algorithm - cont'd

Algorithm (Dimension Reduction using Laplacian Eigenmaps-cont'd)

Output Construct the $d \times n$ matrix Y,

$$Y = \begin{bmatrix} e_2^T \\ \vdots \\ e_{d+1}^T \end{bmatrix} D^{-1/2}$$

The new geometric graph is obtained by converting the columns of Y into n d-dimensional vectors:

$$\left[\begin{array}{cccc} y_1 & | & \cdots & | & y_n \end{array}\right] = Y$$

Output: $\{y_1, \cdots, y_n\} \subset \mathbb{R}^d$.

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Dimension Reduction using Isomaps Algorithm

Algorithm (Dimension Reduction using Isomap)

Input: A geometric graph $\{x_1, x_2, \dots, x_n\} \subset \mathbb{R}^N$. Parameters: neighborhood size K and dimension d.

O Construct the symmetric matrix *S* of squared pairwise distances:

- Construct the sparse matrix T, where for each node i find the nearest K neighbors \mathcal{V}_i and set $T_{i,j} = ||x_i x_j||_2$, $j \in \mathcal{V}_i$.
- **2** For any pair of two nodes (i, j) compute $d_{i,j}$ as the length of the shortest path, $\sum_{p=1}^{L} T_{k_{p-1},k_p}$ with $k_0 = i$ and $k_L = j$, using e.g. Dijkstra's algorithm.

3 Set
$$S_{i,j} = d_{i,j}^2$$
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Dimension Reduction using Isomaps Algorithm - cont'd

Algorithm (Dimension Reduction using Isomap - cont'd)

2 Compute the Gram matrix G:

$$\rho = \frac{1}{2n} \mathbf{1}^T \cdot S \cdot \mathbf{1} , \quad \nu = \frac{1}{n} (S \cdot \mathbf{1} - \rho \mathbf{1})$$

$$G = \frac{1}{2}\nu \cdot 1^{T} + \frac{1}{2}1 \cdot \nu^{T} - \frac{1}{2}S$$

So Find the top d eigenvectors of G, say e_1, \dots, e_d so that $GE = E\Lambda$, form the matrix Y and then collect the columns:

$$Y = \Lambda^{1/2} \begin{bmatrix} e_1^T \\ \vdots \\ e_d^T \end{bmatrix} = \begin{bmatrix} y_1 & | & \cdots & | & y_n \end{bmatrix}$$

Output: $\{y_1, \cdots, y_n\} \subset \mathbb{R}^d$.

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