

# Lecture 1: Graphs, Adjacency Matrices, Graph Laplacian

**Radu Balan**

January 31, 2017

# Definitions

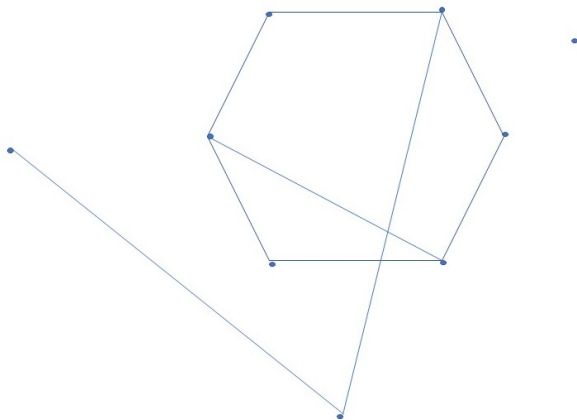
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An *undirected graph*  $G$  is given by two pieces of information: a set of *vertices*  $\mathcal{V}$  and a set of *edges*  $\mathcal{E}$ ,  $G = (\mathcal{V}, \mathcal{E})$ .

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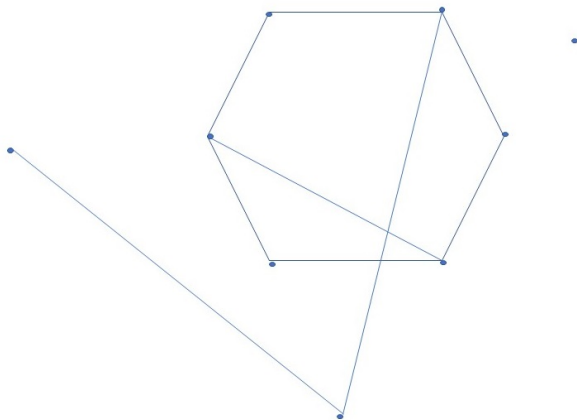
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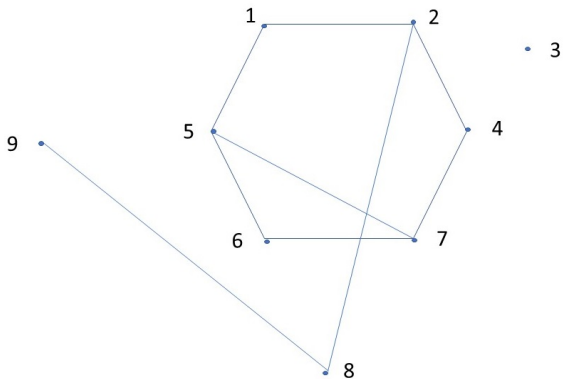


$$\mathcal{V} = ?$$

$$\mathcal{E} = ?$$

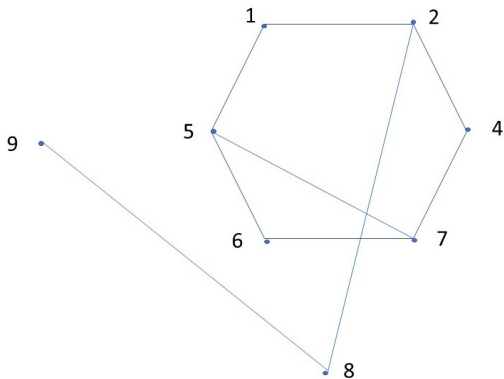
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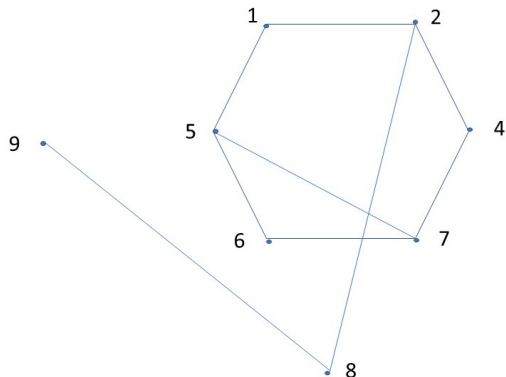
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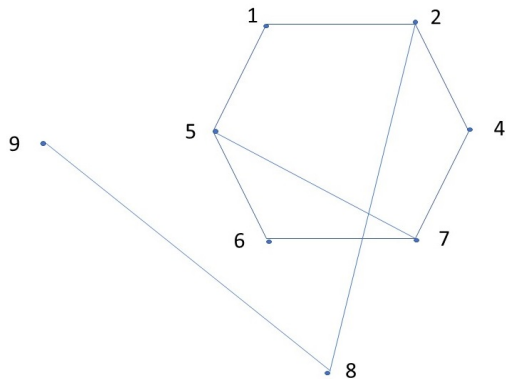


$$\mathcal{V} = \{1, 2, 3, 4, 5, 6, 7, 8, 9\}$$

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$n = 9$  vertices

$m = 9$  edges



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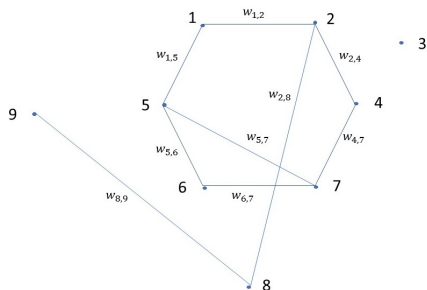
- **Directed Graphs:** In a directed graph, edges are oriented. In general  $(i, j) \not\sim (j, i)$ .
- **Weighted Graphs:** Each edge has an associated weight. A weighted graph is defined by a triple  $(\mathcal{V}, \mathcal{E}, w)$ , where  $w : \mathcal{E} \rightarrow \mathbb{R}$  is a weight function.

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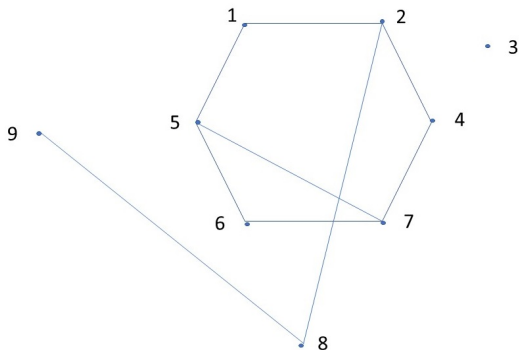


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## Paths

Concept: A **path** is a sequence of edges where the right vertex of one edge coincides with the left vertex of the following edge.

Example:

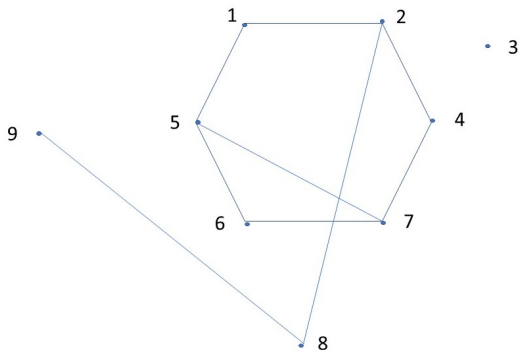


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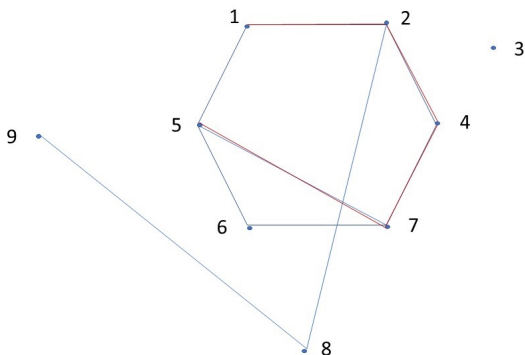
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Graph Attributes (Properties):

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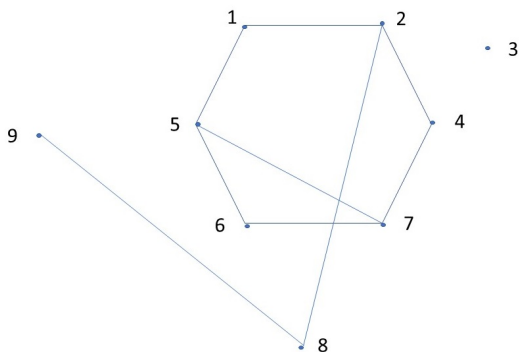
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A complete graph with  $n$  vertices has  $m = \binom{n}{2} = \frac{n(n-1)}{2}$  edges.

# Definitions

## Graph Attributes

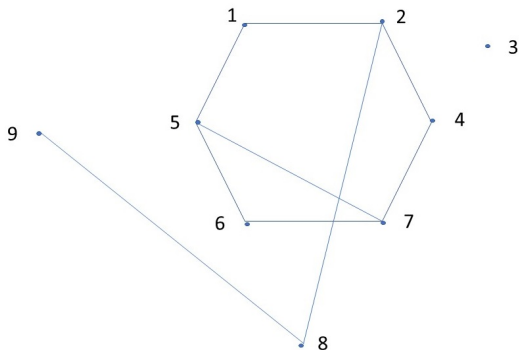
Example:



# Definitions

## Graph Attributes

Example:



- This graph is not connected.
- It is not complete.
- It is the union of two connected graphs.

# Definitions

## Metric

**Distance between vertices:** For two vertices  $x, y$ , the distance  $d(x, y)$  is the length of the shortest path connecting  $x$  and  $y$ . If  $x = y$  then  $d(x, x) = 0$ .

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In a complete graph the distance between any two distinct vertices is 1.

The converses are also true:

- 1 If  $\forall x, y \in \mathcal{E}, d(x, y) < \infty$  then  $(\mathcal{V}, \mathcal{E})$  is connected.
- 2 If  $\forall x \neq y \in \mathcal{E}, d(x, y) = 1$  then  $(\mathcal{V}, \mathcal{E})$  is complete.

# Definitions

## Metric

**Graph diameter:** The diameter of a graph  $G = (\mathcal{V}, \mathcal{E})$  is the largest distance between two vertices of the graph:

$$D(G) = \max_{x,y \in \mathcal{V}} d(x,y)$$

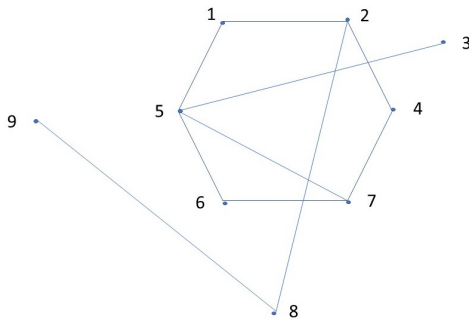
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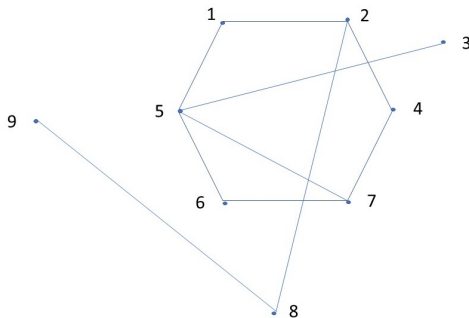
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Example:



$$D = 5 = d(6,9) = d(3,9)$$

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## The Adjacency Matrix

For a graph  $G = (\mathcal{V}, \mathcal{E})$  the **adjacency** matrix is the  $n \times n$  matrix  $A$  defined by:

$$A_{i,j} = \begin{cases} 1 & \text{if } (i,j) \in \mathcal{E} \\ 0 & \text{otherwise} \end{cases}$$

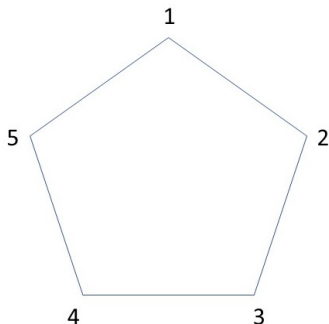
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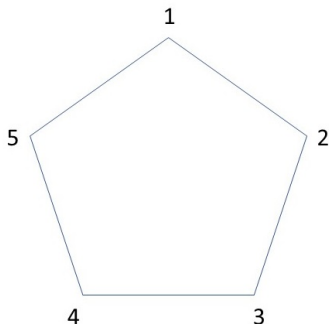
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Example:



$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

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$$A^T = A$$

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For weighted graphs  $G = (\mathcal{V}, \mathcal{E}, W)$ , the **weight** matrix  $W$  is simply given by

$$W_{i,j} = \begin{cases} w_{i,j} & \text{if } (i,j) \in \mathcal{E} \\ 0 & \text{otherwise} \end{cases}$$

# Vertex Degree

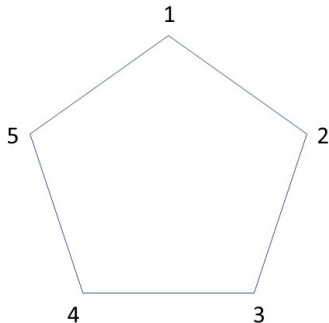
 $d(v)$ 

For an undirected graph  $G = (\mathcal{V}, \mathcal{E})$ , let  $d(v)$  denote the number of edges at vertex  $v \in \mathcal{V}$ . The number  $d(v)$  is called the **degree** (or valency) of vertex  $v$ .

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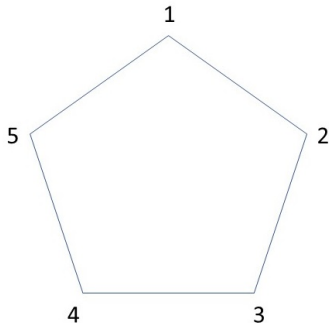




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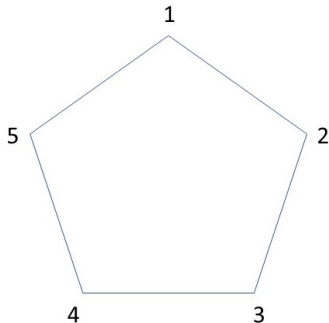


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$$\text{Note: } d(i) = \sum_{j=1}^5 A_{i,j}$$

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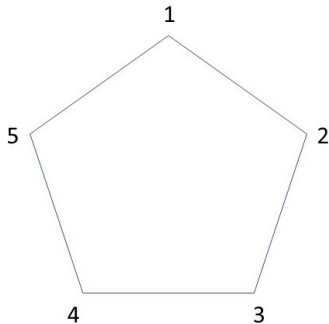
## Matrix $D$

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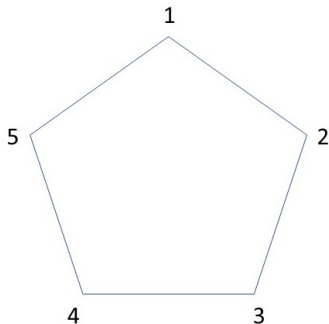
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$$A = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$

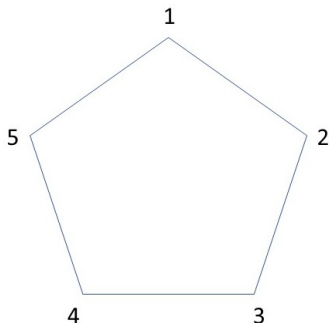
# Graph Laplacian

 $\Delta$ 

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$$\Delta = D - A$$

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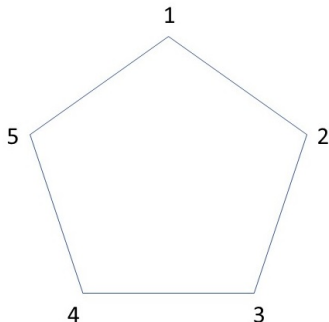
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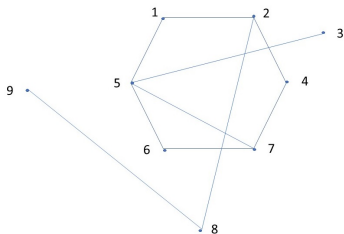
Example:



$$\Delta = \begin{bmatrix} 2 & -1 & 0 & 0 & -1 \\ -1 & 2 & -1 & 0 & 0 \\ 0 & -1 & 2 & -1 & 0 \\ 0 & 0 & -1 & 2 & -1 \\ -1 & 0 & 0 & -1 & 2 \end{bmatrix}$$

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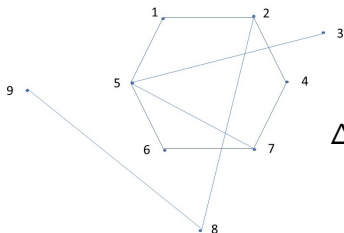
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# Graph Laplacian

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$$\Delta = \begin{bmatrix} 2 & -1 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\ -1 & 3 & 0 & -1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 1 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 2 & 0 & 0 & -1 & 0 & 0 \\ -1 & 0 & -1 & 0 & 4 & -1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & -1 & -1 & 3 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 \end{bmatrix}$$

# Normalized Laplacians



Normalized Laplacian: (using pseudo-inverses)

$$\tilde{\Delta} = D^{-1/2} \Delta D^{-1/2} = I - D^{-1/2} A D^{-1/2}$$

$$\tilde{\Delta}_{i,j} = \begin{cases} 1 & \text{if } i = j \text{ and } d_i > 0 \\ -\frac{1}{\sqrt{d(i)d(j)}} & \text{if } (i,j) \in \mathcal{E} \\ 0 & \text{otherwise} \end{cases}$$

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Normalized Asymmetric Laplacian:

$$L = D^{-1} \Delta = I - D^{-1} A$$

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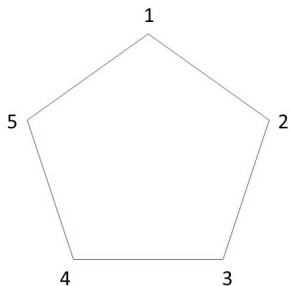
Note:

$$\Delta D^{-1} = I - A D^{-1} = L^T ; \quad (D^{-1})_{kk} = (D^{-1/2})_{kk} = 0 \text{ if } d(k) = 0$$

# Normalized Laplacians

## Example

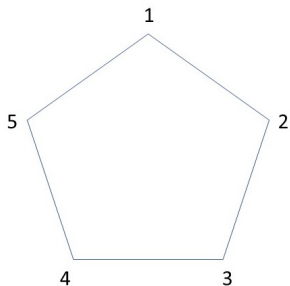
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# Normalized Laplacians

## Example

Example:



$$\tilde{\Delta} = \begin{bmatrix} 1 & -0.5 & 0 & 0 & -0.5 \\ -0.5 & 1 & -0.5 & 0 & 0 \\ 0 & -0.5 & 1 & -0.5 & 0 \\ 0 & 0 & -0.5 & 1 & -0.5 \\ -0.5 & 0 & 0 & -0.5 & 1 \end{bmatrix}$$

# Spectral Analysis

## Eigenvalues and Eigenvectors

Recall the **eigenvalues** of a matrix  $T$  are the zeros of the characteristic polynomial:

$$p_T(z) = \det(zI - T) = 0.$$

There are exactly  $n$  eigenvalues (including multiplicities) for a  $n \times n$  matrix  $T$ . The set of eigenvalues is called its *spectrum*.

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**Remark.** Since  $\det(A_1 A_2) = \det(A_1) \det(A_2)$  and  $L = D^{-1/2} \tilde{\Delta} D^{1/2}$  it follows that  $\text{eigs}(\tilde{\Delta}) = \text{eigs}(L) = \text{eigs}(L^T)$ .

# Spectral Analysis

## Rayleigh Quotient

Recall the following result:

### Theorem

Assume  $T$  is a real symmetric  $n \times n$  matrix. Then:

- 1 All eigenvalues of  $T$  are real numbers.
- 2 There are  $n$  eigenvectors that can be normalized to form an orthonormal basis for  $\mathbb{R}^n$ .
- 3 The largest eigenvalue  $\lambda_{\max}$  and the smallest eigenvalue  $\lambda_{\min}$  satisfy

$$\lambda_{\max} = \max_{x \neq 0} \frac{\langle Tx, x \rangle}{\langle x, x \rangle}, \quad \lambda_{\min} = \min_{x \neq 0} \frac{\langle Tx, x \rangle}{\langle x, x \rangle}$$

# Spectral Analysis

## Rayleigh Quotient

For two symmetric matrices  $T, S$  we say  $T \leq S$  if  $\langle Tx, x \rangle \leq \langle Sx, x \rangle$  for all  $x \in \mathbb{R}^n$ .

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Consequence 3 can be rewritten:

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Consequence 3 can be rewritten:

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In particular we say  $T$  is positive semidefinite  $T \geq 0$  if  $\langle Tx, x \rangle \geq 0$  for every  $x$ .

It follows that  $T$  is positive semidefinite if and only if every eigenvalue of  $T$  is positive semidefinite (i.e. non-negative).

## References

-  B. Bollobás, **Graph Theory. An Introductory Course**, Springer-Verlag 1979. **99**(25), 15879–15882 (2002).
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